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November 4, 2015

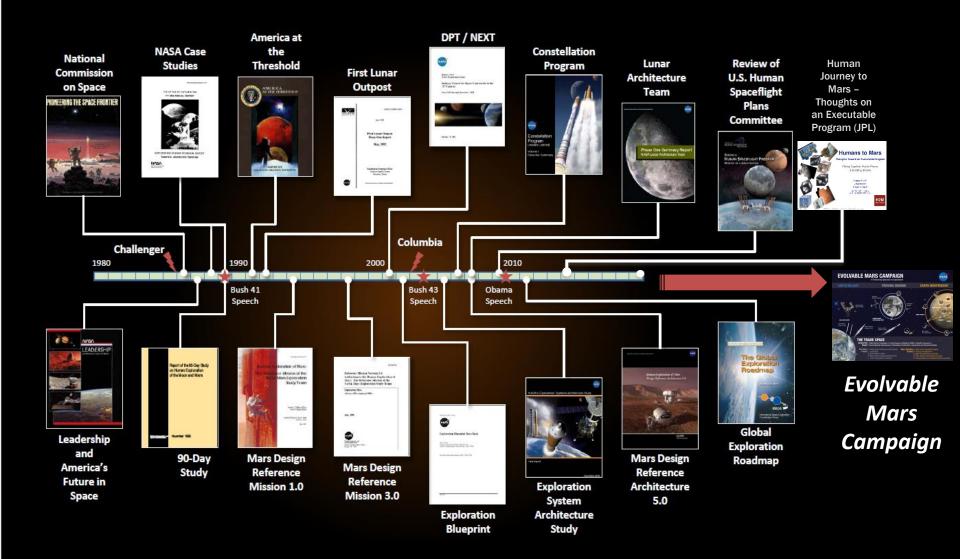
Strategic Principles for Sustainable Exploration



- Implementable in the near-term with the buying power of current budgets and in the longer term with budgets commensurate with economic growth;
- Exploration enables science and science enables exploration, leveraging robotic expertise for human exploration of the solar system
- Application of high Technology Readiness Level (TRL) technologies for near term missions, while focusing sustained investments on technologies and capabilities to address challenges of future missions;
- Near-term mission opportunities with a defined cadence of compelling and integrated human and robotic missions providing for an incremental buildup of capabilities for more complex missions over time;
- Opportunities for *U.S. commercial business* to further enhance the experience and business base;
- Resilient architecture featuring multi-use, evolvable space infrastructure, minimizing unique major developments, with each mission leaving something behind to support subsequent missions; and
- Substantial new international and commercial partnerships, leveraging the current International Space Station partnership while building new cooperative ventures.

A Brief History of Beyond-LEO Spaceflight Architecture Development





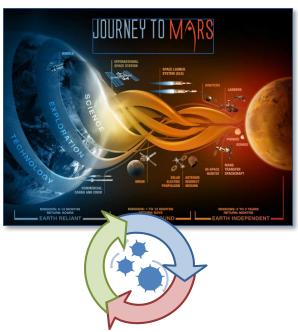
Design Reference Missions vs Design Philosophy







- Internal NASA and other Government
- International Partners
- Commercial and Industrial
- Academic
- Technology developments
- Science discoveries



Evolvable Mars Campaign

- An ongoing series of architectural trade analyses that we are currently executing to define the capabilities and elements needed for a sustainable human presence on Mars
- Builds off of previous studies and ongoing assessments
- Provides clear linkage of current investments (SLS, Orion, etc.) to future capability needs

EVOLVABLE MARS CAMPAIGN

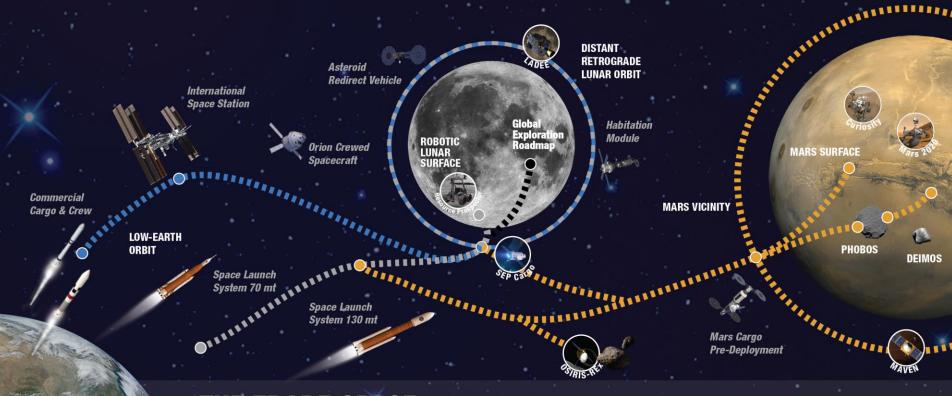
A Pioneering Approach to Exploration



EARTH RELIANT

PROVING GROUND

EARTH INDEPENDENT



THE TRADE SPACE

Across the | Solar Electric Propulsion • In-Situ Resource Utilization (ISRU) • Robotic Precursors • Board | Human/Robotic Interactions • Partnership Coordination • Exploration and Science Activities

Trades

- **Cis-lunar** | Deep-space testing and autonomous operations
 - Extensibility to Mars
 - Mars system staging/refurbishment point and trajectory analyses

Trades

- Mars Vicinity | Split versus monolithic habitat
 - Cargo pre-deployment
 - · Mars Phobos/Deimos activities
 - Entry descent and landing concepts
 - Transportation technologies/trajectory analyses

Evolvable Mars Campaign

EMC Goal: Define a pioneering strategy and operational capabilities that can extend and sustain human presence in the solar system including a human journey to explore the Mars system starting in the mid-2030s.

Identify a plan that:

- Expands human presence into the solar system to advance exploration, science, innovation, benefits to humanity, and international collaboration.
- Provides different future scenario options for a range of capability needs to be used as guidelines for near term activities and investments
 - In accordance with key strategic principles
 - Takes advantage of capability advancements
 - Leverages new scientific findings
 - Flexible to policy changes
- Identifies linkages to and leverage current investments in ISS, SLS, Orion, ARM, short-duration habitation, technology development investments, science activities
- Emphasizes prepositioning and reuse/repurposing of systems when it makes sense
 - Use location(s) in cis-lunar space for aggregation and refurbishment of systems

Internal analysis team members:

- ARC, GRC, GSFC, HQ, JPL, JSC, KSC, LaRC and MSFC
- HEOMD, SMD, STMD, OCS and OCT

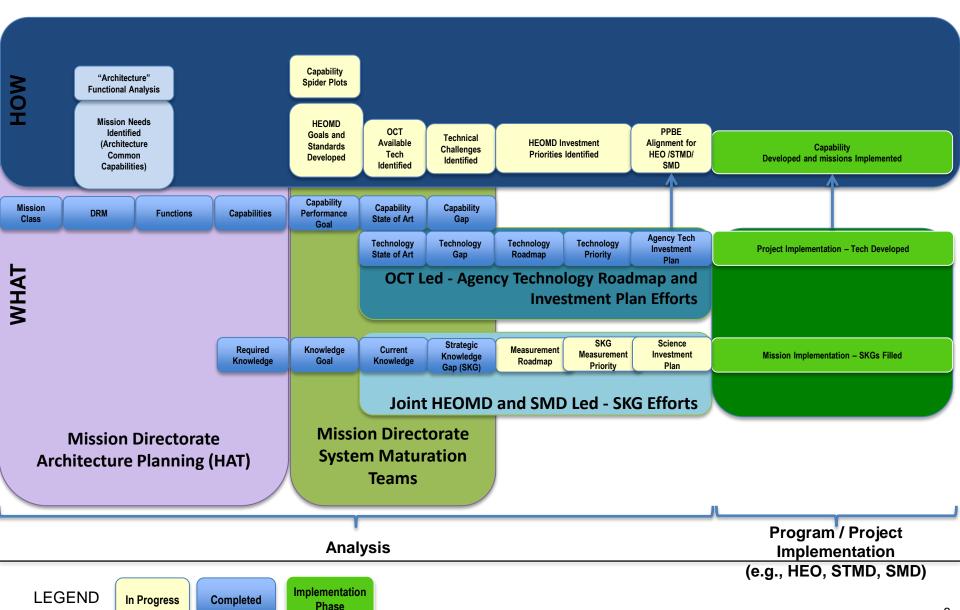
External inputs from:

International partners, industry, academia, SKG analysis groups

EMC Assessment Capability Requires Breadth and Depth Campaign Analysis, Timelines and Decision Needs Congress NAC Int'l Industry **Partners** Public Phobos ARRM Mars 2020 Mission Operations Development Landing Site Selection and Layout **Trajectory and Orbit Analysis Proving Ground Ops Destination Operations Element Conceptualization and Design** In-space **Destination Systems Habitat Sizing** Lander Mars Ascent Vehicle Design **Transportation Systems** Capability Needs Analysis Performance Parameter **Strategic Planning** Definition **STMD** ISS **ESD AES** NASA Decision Processes, Technology Roadmaps & Capability Gap Analysis and Strategic Investment Plan Pioneering Space Challenges Roadmap Development

NASA Technology Roadmaps & Investment Plan





EARTH RELIANT

NEAR-TERM OBJECTIVES

DEVELOP AND VALIDATE EXPLORATION CAPABILITIES IN AN IN-SPACE ENVIRONMENT

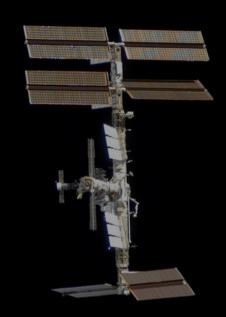
- Long duration, deep space habitation systems
- Next generation space suit
- Autonomous operations
- Communications with increased delay
- Human and robotic mission operations
- Operations with reduced logistics capability
- Integrated exploration hardware testing

LONG-DURATION HUMAN HEALTH EVALUATION

- Evaluate mitigation techniques for crew health and performance in micro-g space environment
- Acclimation from zero-g to low-g

COMMERCIAL CREW TRANSPORTATION

Acquire routine U.S. crew transportation to LEO



PROVING GROUND OBJECTIVES



Enabling Human Missions to Mars



TRANSPORTATION



WORKING IN SPACE



STAYING HEALTHY

- Heavy Launch
 Capability: beyond
 low-Earth orbit launch
 capabilities for crew, co manifested payloads,
 large cargo
- <u>Crew</u>: transport at least four crew to cislunar space
- In-Space Propulsion: send crew and cargo on Mars-class mission durations and distances

- ISRU: Understand the nature and distribution of volatiles and extraction techniques and decide on their potential use in human exploration architecture.
- Deep-space operations capabilities: EVA, Staging, Logistics, Human-robotic integration, Autonomous operations
- <u>Science</u>: enable science community objectives

- Deep-Space
 <u>Habitation</u>: beyond low-Earth orbit habitation systems sufficient to support at least four crew on Mars-class mission durations and dormancy
- Crew Health: Validate crew health, performance and mitigation protocols for Mars-class missions

Demand Areas for Pioneering Space: Steps on the Journey to Mars



	Mission Demand Areas	ISS	Cis-lunar Short Stay (e.g. ARM)	Cis-lunar Long Stay	Cis-Mars Robotic	Orbital Proving Ground	Mars Operational
ce and	In Situ Resource Utilization & Surface Power		Exploratory ISRU Regolith	Exploratory ISRU	Exploratory ISRU & Atmosphere	Exploratory ISRU	Operational ISRU & High Power
ng in Spa On Mars	Habitat & Mobility		Initial Short Duration	Long Duration		Resource Site Survey	Long Duration / Range
Working in Space and On Mars	Human/Robotic & Autonomous Ops	System Testing	Crew-tended	Earth Supervised	Earth Monitored	Autonomous Rendezvous & Dock	Earth Monitored
×	Exploration EVA	System Testing	Limited Duration	Full Duration	Full Duration	Full Duration	Frequent EVA
	Crew Health	Long Duration	Short Duration	Long Duration	Dust Toxicity	Long Duration	Long Duration
Staying Healthy	Environmental Control & Life Support	Long Duration	Short Duration	Long Duration	Long Duration	Long Duration	Long Duration
	Radiation Safety	Increased Understanding	Forecasting	Forecasting Shelter	Forecasting Shelter	Forecasting Shelter	Forecasting & Surface Enhanced
	Ascent from Planetary Surfaces				Sub-Scale MAV	Sub-Scale MAV	Human Scale MAV
tion	Entry, Descent & Landing				Sub-Scale/Aero Capture	Sub-Scale/Aero Capture	Human Scale EDL
orta	In-space Power & Prop		Low power	Low Power	Medium Power	Medium Power	High Power
Transportation	Beyond LEO: SLS & Orion		Initial Capability	Initial Capability	Full Capability	Full Capability	Full Capability
Tra	Commercial Cargo & Crew	Cargo/Crew	Opportunity	Opportunity	Opportunity	Opportunity	Opportunity
	Communication & Navigation	RF	RF & Initial Optical	Optical	Deep Space Optical	Deep Space Optical	Deep Space Optical
		EARTH RELIANT		PROVING G	ROUND		EARTH INDEPENDENT

System Maturation Teams - Integrated capability investment decisions with traceability to human exploration needs



System Maturation Team
Autonomous Mission Operations (AMO)
Communication and Navigation (Comm/Nav)
Crew Health & Protection and Radiation (CHP)
Environmental Control and Life Support Systems and Environmental Monitoring (ECLSS-EM)
Entry, Descent and Landing (EDL)
Extra-vehicle Activity (EVA)
Fire Safety
Human-Robotic Mission Operations
In-Situ Resource Utilization (ISRU)
Power and Energy Storage
Propulsion
Thermal (including cryo)
Discipline Team - Crosscutting
Avionics
Structures, Mechanisms, Materials and Processes (SMMP)

- A key piece to the Pioneering Space strategy is input from System Maturation Teams (SMTs). The SMTs comprise subject matter experts from across the agency who have been involved in maturing systems and advancing technology readiness for NASA.
- The SMTs are defining performance parameters and goals for each of the 14 capabilities, developing maturation plans and roadmaps for the identified performance gaps, specifying the interfaces between the various capabilities, and ensuring that the capabilities mature and integrate to enable future pioneering missions. The subject matter experts that compose each SMT are responsible for understanding their capabilities across all missions and elements within the Evolvable Mars Campaign.
- The SMTs work closely with the Evolvable Mars Campaign to coordinate capability needs and gaps.

TRANSPORTATION OF CREWAND CARGO TO/FROM DEEP SPACE



LIVING IN SPACE: HABITATION



Challenges

Protect and support crew in deep space for up to 60 days (cislunar) or 1100 days (Mars vicinity)

Uncrewed operations during deployment and between uses

Reduced logistics and spares

Earth-independent operations

Phobos Habitat

Live and operate in microgravity at Phobos

- ✓ 4 crew for up to approx. 500 days
- √ 48 m³ volume for logistics and spares
- ✓ Logistics Mass: 10.7 t
- ✓ EVA system with Phobos mobility and dust mitigation
- √ 4-5 years dormant before use
- √ 3 years dormant between uses

Common Capabilities

4 Crew for 500-1100 days Common pressure vessel

15 year lifetime with long dormancy periods

Design for reusability across multiple missions

100 m³ habitable volume and dry mass < 22 t

Autonomous vehicle health monitoring and repair

Advanced Exploration ECLSS with >85% H₂O recovery and 50% O₂ recovery from reduced CO₂

ECLSS System (w/o spares): <5 t mass, <9 m² volume, <4 kW power

Environmental monitoring with >80% detection rate without sample return

14-kW peak operational power and thermal management required

Autonomous mission operations with up to 24 minute one-way time delay

Autonomous medical care, behavioral health countermeasures, and other physiological countermeasures to counteract long duration missions without crew abort

Exercise equipment under 500 kg

Provide 20-40 g/cm² of radiation protection

EVA pressure garment and PLSS <200 kg

Contingency EVA operations with 1 x 2-person EVA per month

Communications to/from Earth and between elements

Mars Surface Habitat

Live and operate on the Mars surface in 1/3 g

- ✓ 4 crew for up to approx. 500 days
- √ 48 m³ volume for logistics and spares
- ✓ Logistics Mass: 10.7 t
 - √ 4 years dormant before use
 - 3-4 years dormant between uses
 - ✓ EVA system with surface mobility, dust mitigation, and atmospheric compatibility

Transit Habitat

Live and operate in microgravity during trip to/from Mars

- √ 4 crew for up to 1,100 days
- √ 93 m³ volume for logistics and spares
- ✓ Logistics Mass: 21 t
 - ✓ 4 years dormant before use and between uses

Any initial, short-duration habitation module in the Proving Ground of cislunar space will serve as the initial building block required for Mars-class habitation

IN-SPACE TRANSPORTATION

Mars EDL

Challenges



Transport crew and cargo to/from Mars vicinity

Provide transportation within the Mars system

Provide access to Mars surface

Uncrewed operations during deployment and between uses

Deliver crew and cargo to Mars surface

- ✓ Possible aerocapture at 6.3 km/s if not propulsively. delivered to orbit
- ✓ Entry velocity of 3.8 4.7 km/s
- √ 100 m precision landing with hazard avoidance
- ✓ Supersonic retropropulsion with LOX/CH₄ engine
- ✓ Deployable/Inflatable (16-23 m) entry systems
- ✓ Surface access at +2 km MOLA
- ✓ 20-30 t payload to the surface, 40-60 t arrival at Mars

Common Capabilities

Chemical Propulsion

Common LOX/CH4 Pump-Fed Engine:



- ✓ Thrust: 25 klbf
- ✓ Isp: 355-360 s
- Up to 15 year lifetime
- 150-500 s burn time
- 5:1 throttling
- ✓ Near-ZBO storage with 90 K cryocooler

LOX/CH, Pressure-Fed RCS:

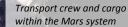
✓ Thrust: 100-1000 lbf; Isp: 320 s

Mars Ascent

Return crew and cargo from Mars surface

- √ 4 crew and 250 kg payload from ±30 deg latitude, 0 km MOLA to Mars parking orbit
- ✓ 26 t prop (20 t O₂, 6 t CH₄), 35 t total liftoff mass, 8 t Earth launch dry mass
- ✓ Up to 3 days flight duration
- √ 5 years dormant before use
- ✓ Use of ISRU-produced oxygen

Mars Taxi



- ✓ 4 crew for up to 2.5 days
- √ 7 t inert mass. 14 t wet mass.
- √ 8 kW EOL at Mars solar power
- ✓ Reusable and refuelable

Electric Propulsion

Deliver approx. 40-60 t to Mars orbit

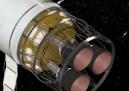
200-kW class solar array system (BOL at 1 AU) using 30% efficient GaAs, triple junction solar cells

300 V array system converted to 800 V for EP and 28 V for spacecraft

ARRM-Derived Hall Thruster:

- ✓ Common Xe storage and feed system with 13.3 kW thruster
- ✓ Isp: 2000 s or 3000 s modes





crew and cargo to Mars vicinity

Combined SEP and hypergolic propulsion system delivers

✓ 2 x 200-kW class arrays

SEP - Hybrid

- √ 1,100 days total trip mission time, 300 days at
 - √ >16 kW thermal rejection
 - ✓ Ability to refuel 24 t of Xe on orbit
 - √ 15 year lifetime, 3 uses, 3

refuelings

√ 1 x 200-kW class solar array √ >8 kW thermal rejection

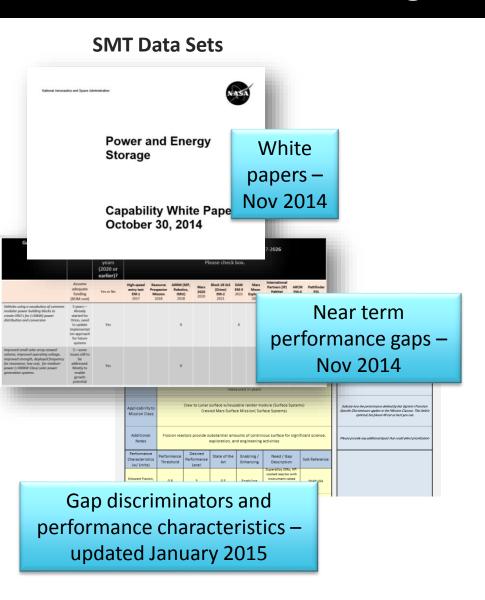
SEP delivers cargo to Mars vicinity, and LOX/CH

propulsion delivers crew to/from Mars vicinity

- ✓ Flight times to Mars approx. 1,400 days
- √ 4-6 years dormant before use

Data collection and usage





EMC Data Set

		Elen	ment and Year	
Design Constraint/ Parameter	Units	Phobas Power System (Mike G.) 2028	Stationary Mars Surface Power (Larry) 2034	Deployed/Mobile Mars Surface Power (Larry) 2034
fission Parameters				
Element Lifetime	yrs	10+	10	10+ years
Destination		Phobos surface	Mars Surface, 1 km from Crew Ops	Mars Surface, TBD km from Landers
Packaged Diameter	m	7.2	TBD. May be a single, large (3.3 m) unit or multiple, smaller (1.2 – 1.5 m) diameter units	TBD
Packaged Length	m	5	TBD. May be a single, large (7 m) unit or multiple, smaller (4 – 5 m) long units	тво
'ower				
Power Generation Type		solar	Fission Surface Power	Solar Array
BOL Capability	kW	125 kW SEP solar arrays (produce orbital average of 25 kW)	TBD (>40kW total)	0.2
EOL Capability	kW	,	40 total; evaluating single	
Degradation Rate	%/yr	Do	rforma	anco
Power Storage Type		lithiu		alice
BOL Capacity	kW-hr	1		
		pa	arame [.]	ters

SMT and EMC Performance Metrics Validation

		EMC Performance Parameters				
Cap	Discrm	Gap	Where needed?	Performance		
υÆ	Dis			Desired	SOA	
Explora tion PLSS	Surface EVA	PLSS Compatibility with Exploration architecture – Mars atmosphere	Mars surface	Recharge services	EMU	EAM, Phobos hab,
Exploration EVA Avionics		PLSS avionics system		*Vehicle-born HL comm		Transit hab, Mars
	Avionics	PGS avionics system	With PLSS/PGS	*A dual-band radio (UHF for mission critical data and 802.11 variant	EMU	surface, and all mobility EMC specified the same
	Avic	Avionics systems for EVA tasks	Any surface EVA	protocol S-Band for high rate) *Separate HD camera connected via 802.11 Wi-Fi or dual-band radio	EMU	avionics as the SMT
e VA	e and	Long duration EVA Maintenance (>28 days)	Long duration surface	TBD hours MPT, Maintenance Area	EMU	Phobos hab and Mars surface hab
Exploration EVA Architecture	Suit Maintenance and Planetary Protection	Non-suit dust mitigation	Any geologic work (includes ARCM)	Partner with ECLSS & vehicle teams to mitigate dust, ingress/egress	Suits leak/ve	Need operational concepts, architecture (specifications of suitport
EXF	Suit N Plane	Planetary protection (forward and backward)	Phobos, Mars	methods, operations (special regions)	nt	or airlock) No parameters specified
EVA Integrati on	Rescue	Integrated rescue operations	All EVA operations	Depends on ops and vehicle architecture		No 'acceptable' levels of dust identified

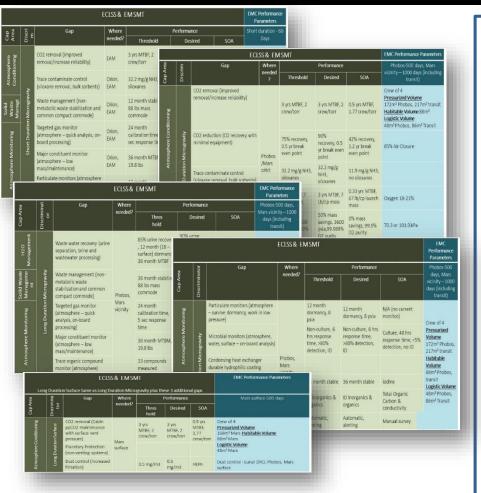
Example Capability Gap Data Capture: ECLSS



		ECLS	SS & EM	SMT			EMC Performance Parameters
Area	ri E	Gap	Where		Phobos-500 days, Mars		
Cap Area	Discrim		needed ?	Threshold	Desired	SOA	vicinity—1000 days (including transit)
ditioning		CO2 removal (improved removal/increase reliability)		3 yrs MTBF, 2 crew/torr	3 yrs MTBF, 2 crew/torr	0.5 yrs MTBF, 1.77 crew/torr	Crew of 4 Pressurized Volume 172m³ Phobos, 217m³ transit Habitable Volume 88m³ Logistic Volume 48m³ Phobos, 86m³ Transit
Atmosphere Conditioning	Long Duration Microgravity	CO2 reduction (O2 recovery with minimal equipment)	Phobos	75% recovery, 0.5 yr break even point	90% recovery, 0.5 yr break even point	42% recovery, 1.2 yr break even point	85% Air Closure
Atn	g Duration	Trace contaminate control (siloxane removal, bulk sorbents)	/Mars orbit	32.2 mg/g NH3, siloxanes	32.2 mg/g NH3, siloxanes	11.9 mg/g NH3, no siloxanes	
iere re nent		O2 generation system (reduced size and complexity)		3 yrs MTBF,? Lb/cp mass	3 yrs MTBF, ? Lb/cp mass	0.33 yrs MTBF, 67 lb/cp launch mass	Oxygen 18-21%
Atmosphere Pressure Management		High pressure O2 resupply (high frequency EVAs)		50% mass savings, 3600 psia, 99.989% O2 purity	50% mass savings, 3600 psia,99.989% O2 purity	0% mass savings, 99.5% O2 purity	70.3 or 101.3 kPa ₁₇

Environmental Control and Life Support System – Environment Monitoring (ECLSS-EM) SMT



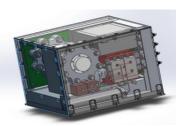


AES – FY16 Activities

- ✓ Life Support Systems:
 Developing improved sorbents for CO₂ removal, High Pressure Oxygen Generation system for replenishing space suits, Cascade Distillation System for waste water processing, and Spacecraft Atmosphere Monitor for detecting trace gas contaminants in ISS air.
- Next Space Technology Exploration Partnerships (NextSTEP): Developing advanced CO₂ removal technologies, modular ECLSS, and hybrid biological and chemical life support systems.
- Feeds forward to short and long duration habitats used for transit and surface destinations.



Cascade Distillation System



Spacecraft Atmosphere Monitor

Life Support Systems:

Completed Systems Requirements Review for Spacecraft Atmosphere Monitor. ISS demo planned in 2018.

Commonality: Advantages and Disadvantages



Advantages

- Reduced cost (one vs. multiple DDT&E)
- Improved safety (common operations)
- Reduced logistics (same spares for different habitats)
- Simplified infrastructure integration (one interface vs. multiple)
- Simplified training (one system vs. multiple)

Disadvantages

- Sub-optimized (each application usually gives up unique attributes)
- May preclude inclusion of latest technology

Space Station Common Module



Inter-modal Cargo Container



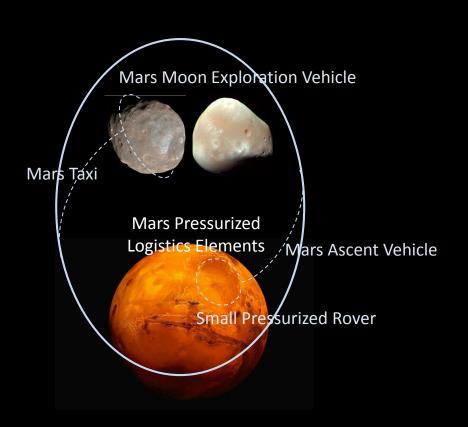






EMC Small Habitat Commonality Scope







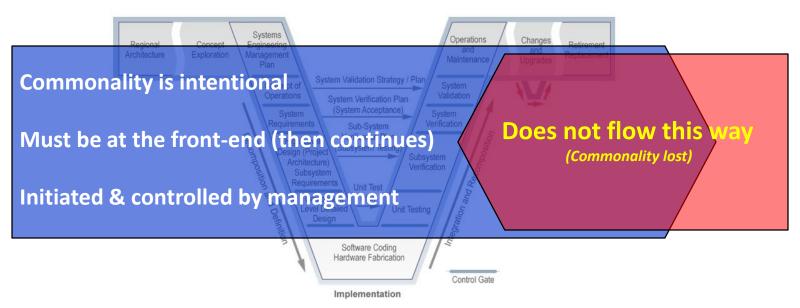




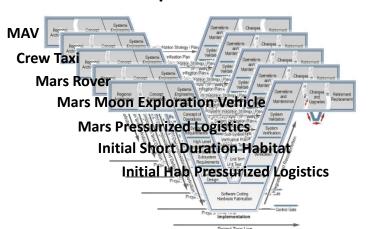
Commonality: Lead From the Start and Never Stop



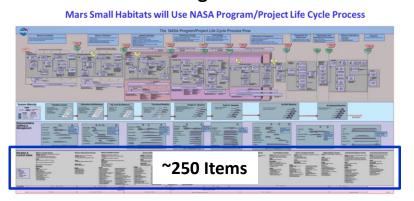
Program Development



Unique DDT&E



NASA Program DDT&E

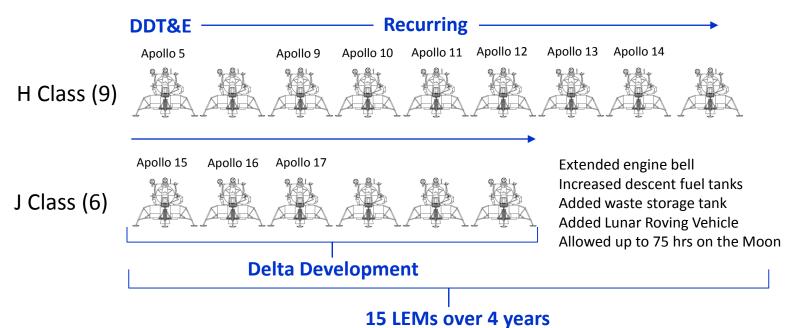


Example of Core Commonality



Apollo Lunar Excursion Module





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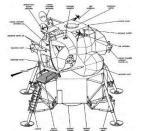
Analogous Small Hab DDT&E vs. Recurring



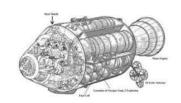


- Small Habitats
- Mission Beyond Low-Earth Orbit
- Gravity and Weightless Operations
- Flight Hardware
- Good Documentation





Command Service Module



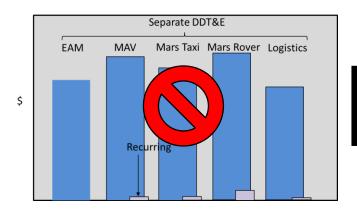
								CSM peak		LEM peak								
	In ¢	000 real yea	r do	llars ->				56%		57%								
	III Ş	1963		1964		1965		1966		1967		1968		1969		1970		
Lunar Module	Ś	123,100		135,000	ė	242,600		310,800	ė	472,500	ė	399,600	ė	326,000	ė	231,433		
Command and Service Module	Ś	345,000		545,874		577,834	Ś	615,000		560,400		455,300		346,000	- 1	282,821		
Inflation Adjustment	,	343,000	,	343,674	7	377,034	,	013,000	Ÿ	300,400	7	455,500	,	340,000	7	202,021		
NASA Inflation Factor to 2015		11.159		10.678		10.327		9.743		9.287		8.812		8.336		7.798		
VOATIMI actor to 2013	In 2	015 dollars	ŚB-			10.327		3.743		3.207		0.012		0.550		7.750	2015 9	UM Ś
Lunar Module	Ś	1.374		1.442	Ś	2,505	Ś	3.028	Ś	4.388	Ś	3.521	Ś	2.718	Ś	1.805		20.78
Command and Service Module	Ś	3.850	-	5.829	Ś		Ś	5.992	-	5.204	_	4.012	Ś	2.884	_	2.205	-	35.94
Estimation	-	Low est.	Ť	High est.	Ť	3.307	Ť	3.332	Ť	5.20	Ť	7.011	Ť	2.001	Ť	2.200		
Total manufactured LEMS		9	П	11.5			(Lo	=Operational	Uni	ts. Apollo 9 ti	hru 1	17: Hi adds 2	.5 ur	nits in varvin	gsta	ges of manu	ufacture)	
Total manufactured CSMs		11		13.5			-	=Operational							-	-		
							-			, ,		,			Las	t two years		
Lunar Module, % of Total that was							П	Land	22	s \$14B	1							
for Manufacture of Units		22%		43%			ш	Lallu	=13	9 3 T4D	- 1					22%	of total	
CSM Module, % of Total that was							П.	then S	70	00M ea.	.							
for Manufacture of Units		14%		44%			U			oivi cu						14%	of total	
								フノ										
	20	15 \$B Hi/Lo	20	15 \$B Lo/Hi	2	015 \$B Avg.		// (`			
LEM, DDTE	\$	16.21	\$	11.91	\$	14.06				Lun	ar	Spaced	raf	ft_				
LEM per Unit	\$	0.398	\$	0.99	\$	0.69						-						
										S26B 1	the	en \$900	ON	l ea.				
CSM DDTE	\$	30.91	\$	20.09	\$	25.50	-	$\overline{}$,		. , ,)			
CSM per Unit	\$	0.37	\$	1.44	ċ	0.91			_									

Objective: Maximize Small Habitat Commonality



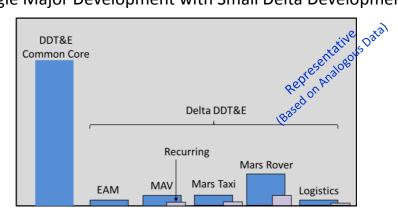
Without Commonality

(Separate Parallel Development)



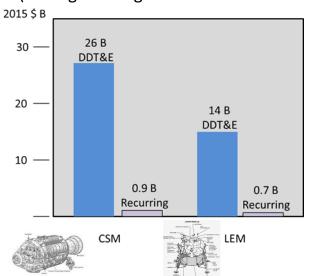
Commonality Objective

(Single Major Development with Small Delta Developments)

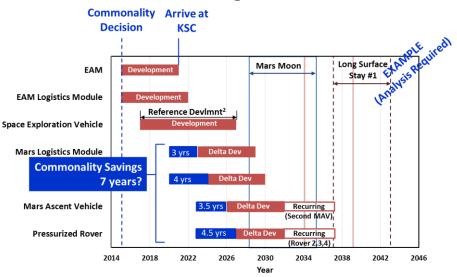


Benefits of Common Core

(Analogous Program DDT&E vs. Recurring)

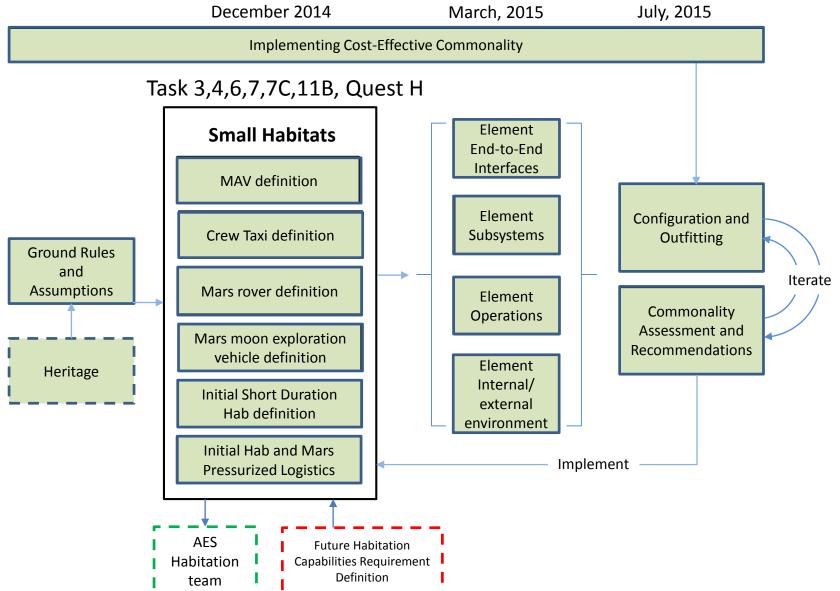


Reduced Program Schedule



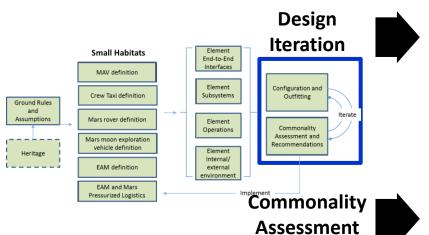
How can we maximize commonality across Mars ascent, Mars vicinity taxi, exploration vehicle and initial deep space habitation component?

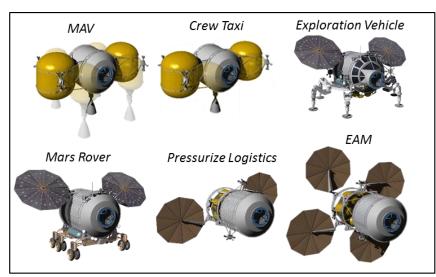


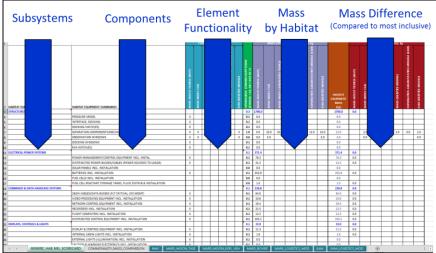


Validate/Assessment Cycle



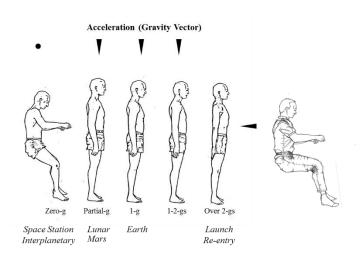


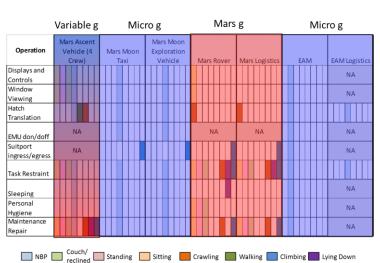


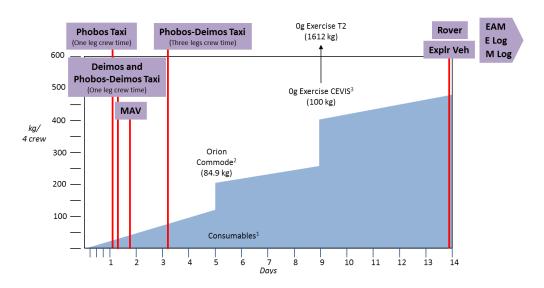


Crew Operating Postures









Transit Phase	Mars Ascent Vehicle	Mars Moon Taxi	Mars Moon Exploration Vehicle	Mars Logistics	Mars Rover	EAM	Logistics
Launch		If Mars Moon Laxi travels with Transit		7777	If crew lands in rovers: 2 suitports,	Airloc cost- Airloc cos bilicals, supportant	logis use pares
DRO staging		He to RG To stee EV Su	M M	7777	mblices,	2-4-50 Swand support sys	EVA c hables,
Transit/outbound		and 4 NACE	2 su tports, umb licals 2	~T2 EVA	st pp int ys	NA NA	NA NA
Mars Orbit	NA NA	Transfer 4 EVA suits	EVA suits and supports per over	ogi dics and opi dics and opares, eVA Consumables	per rover, MA ES dits re- tians errad fo MAV (2 on ea.	NA NA	NA
EDL		NA	1	LOG	Rover)	NA	NA
Surface		NA			ern ver and upparts s	NA	NA
Ascent	Transfer 4 M VCTs*) unblical, and support sys.	NA	NA	NA	NA	NA	NA
Transit/return*	NA	NA	NA	NA	NA	NA	EVA c nables, logi: log pares
DRO*	NA	NA	NA	NA	NA	EVA co ables, logist ares	EVA c nables, logi: pares
Earth Entry*	NA	NA	NA	NA	NA	NA	NA

NextSTEP BAA Overview



- Solicited three critical areas for technology maturation:
 - Advanced Propulsion Systems
 - Habitation Systems (Including Life Support)
 - Small Satellite Missions (EM-1 secondary payloads)



- Facilitates development of deep space human exploration capabilities in the cis-lunar proving ground and beyond
- Continues successful public-private partnership model and spurs commercial endeavors in space
- Selected 12 proposals and will proceed to enter into Fixed Price
 Contracts with technical/payment milestones with private-sector partners
 - Emphasis for eligibility and execution placed on contribution of private corporate resources to the private-public partnership to achieve goals and objectives
 - Selected partners with the technical capability to mature key technologies and demonstrate commitment toward potential commercial application

Proving Ground Top Level Goals

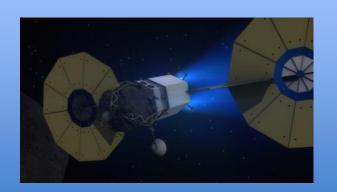
Note- concepts shown are notional



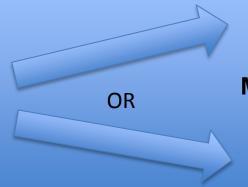
Initial Phase of Proving Ground

End of Proving Ground

In-Space Transportation Evolution



ARM SEP Development





Split SEP / Chemical

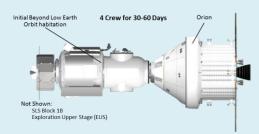
Mars-Class Mission SEP Validation



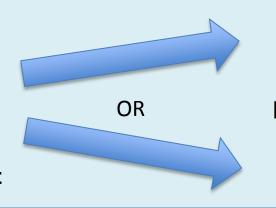
Hybrid SEP / Chemical

Habitat

Long Duration Habitation Evolution



Initial Beyond Low Earth Orbit Habitation Development





Mars-Class Mission Habitation Validation



EMC FY16 Plans

- Interim Results / Mar 2016; Final Results / June 2016



Transportation

- Refinement of Hybrid and SEP/Chem transportation architectures for closure (including proving ground Flight Test Objectives (FTO))
- Sensitivities of additional capability investments for transportation architectures
- Assessments of alternate transportation scenarios as needed

Habitation

- AES Mars Habitat driven design (definition of advanced habitation roadmaps, we know what we need to get to, but don't know how to get there)
- Assessments of alternate habitation system designs (Future Capability Team Modular and BAA commercial) on EMC architecture

Pathfinders

- -EDL path finder strategy and assessment
- Provide Mars Moon SKGs for Mars Orbiter/moon pre-cursor

Tele-operations

 Define low latency tele-operations for Mars Moons and for Mars surface via Mars moons. Link back to FTOs in cis-lunar and ISS

Mars Surface Pioneering

 Develop Surface strategy, capabilities and layout beyond initial boots on Mars that leads to Earth Independence

ISRU

- –An ISRU strategy that begins on ISS, expands to cislunar space, proceeding to the Mars vicinity and ultimately the Mars surface will be developed.
- FTOs and system concepts for each step will be developed

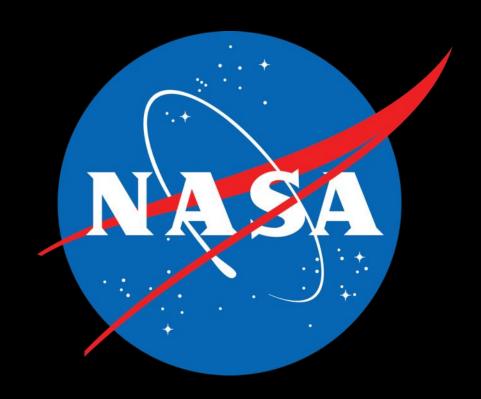
Partnerships and External Engagement

- -FY16 EMC reports
- –Engagement Workshop(s)
- -OCE Engagement / CLT
- -OCT Engagement / Resiliency Studies
- -ISECG Engagement
- -Media Products

Summary



- The Journey to Mars requires a resilient architecture that can embrace new technologies, new international / commercial partners, and identify agency investment choices to be made in the near, mid and long term.
- The Evolvable Mars Campaign:
 - Informs the agency choices by providing technical information from a cross agency, end-to-end integrated analysis
 - Needs to continue to develop linkages to the agency decision making and capability investment processes
- Regardless of which path is ultimately selected, there are a set of common capabilities required to be developed by NASA and its partners over the next 10 years



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